



# Cloud Information Content in EPIC's O<sub>2</sub> A- and B-band channels (680, 688, 764, 780 nm): Two Approaches, Same Conclusions

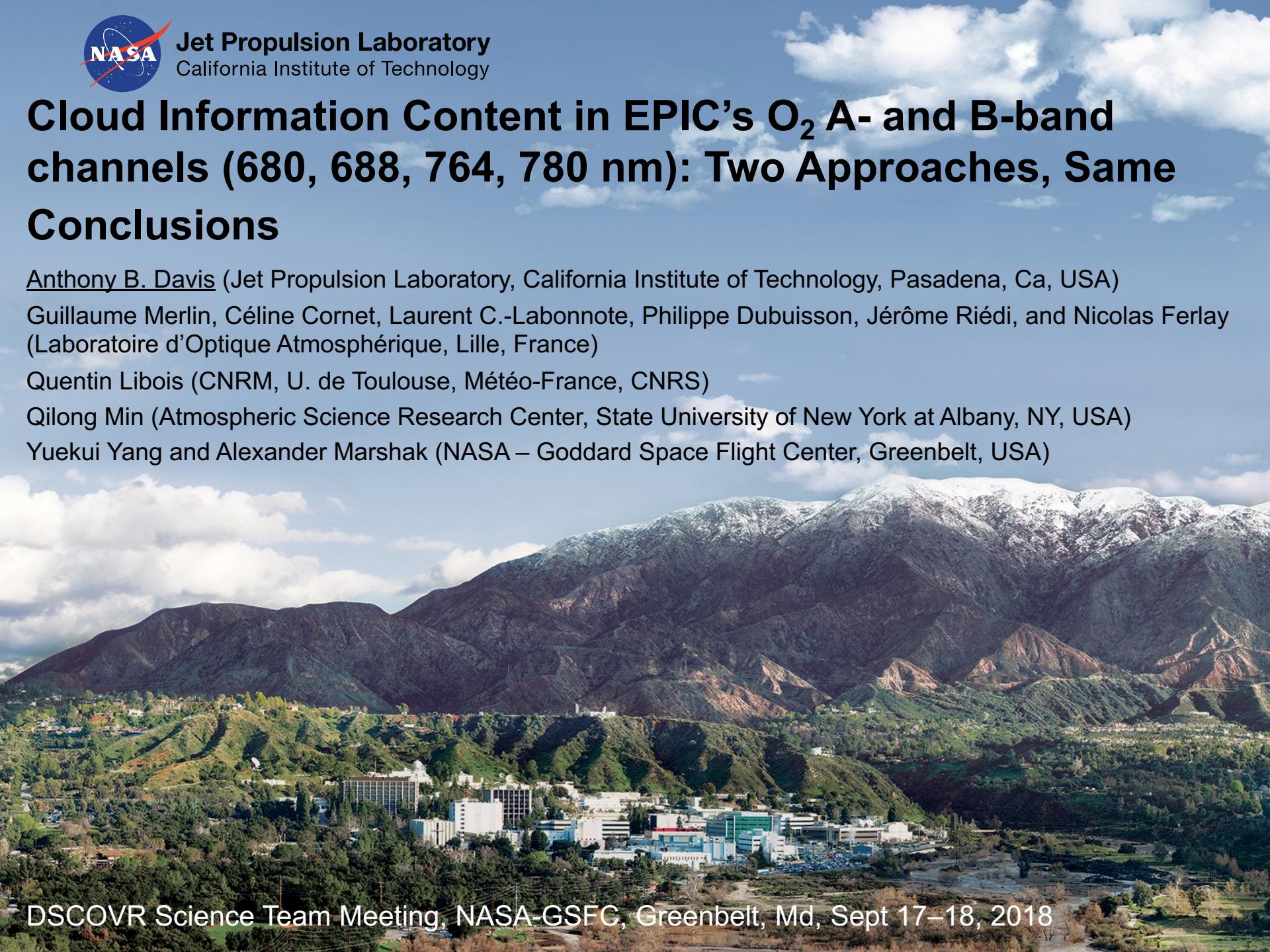
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# Outline

- **Optimal estimation approach**
  - A.B. Davis, G. Merlin, C. Cornet, L. C.-Labonnote, J. Riédi, N. Ferlay, P. Dubuisson, Q. Min, Y. Yang, and A. Marshak. Cloud information content in EPIC/DSCOVR's oxygen A- and B-band channels: An optimal estimation approach. *J. Quant. Spectrosc. Rad. Transf.*, 216, 6-16 (2018).  
<https://doi.org/10.1016/j.jqsrt.2018.05.007>
- **Physics-based approach**
  - A.B. Davis, N. Ferlay, Q. Libois, A. Marshak, Y. Yang, and Q. Min. Cloud information content in EPIC/DSCOVR's oxygen A- and B-band channels: A physics-based approach. *J. Quant. Spectrosc. Rad. Transf.* (2018, in press).  
<https://doi.org/10.1016/j.jqsrt.2018.09.006>
- **Conclusions/outlooks**

# EPIC's A- and B-band channels ... at 11/17 new Moon

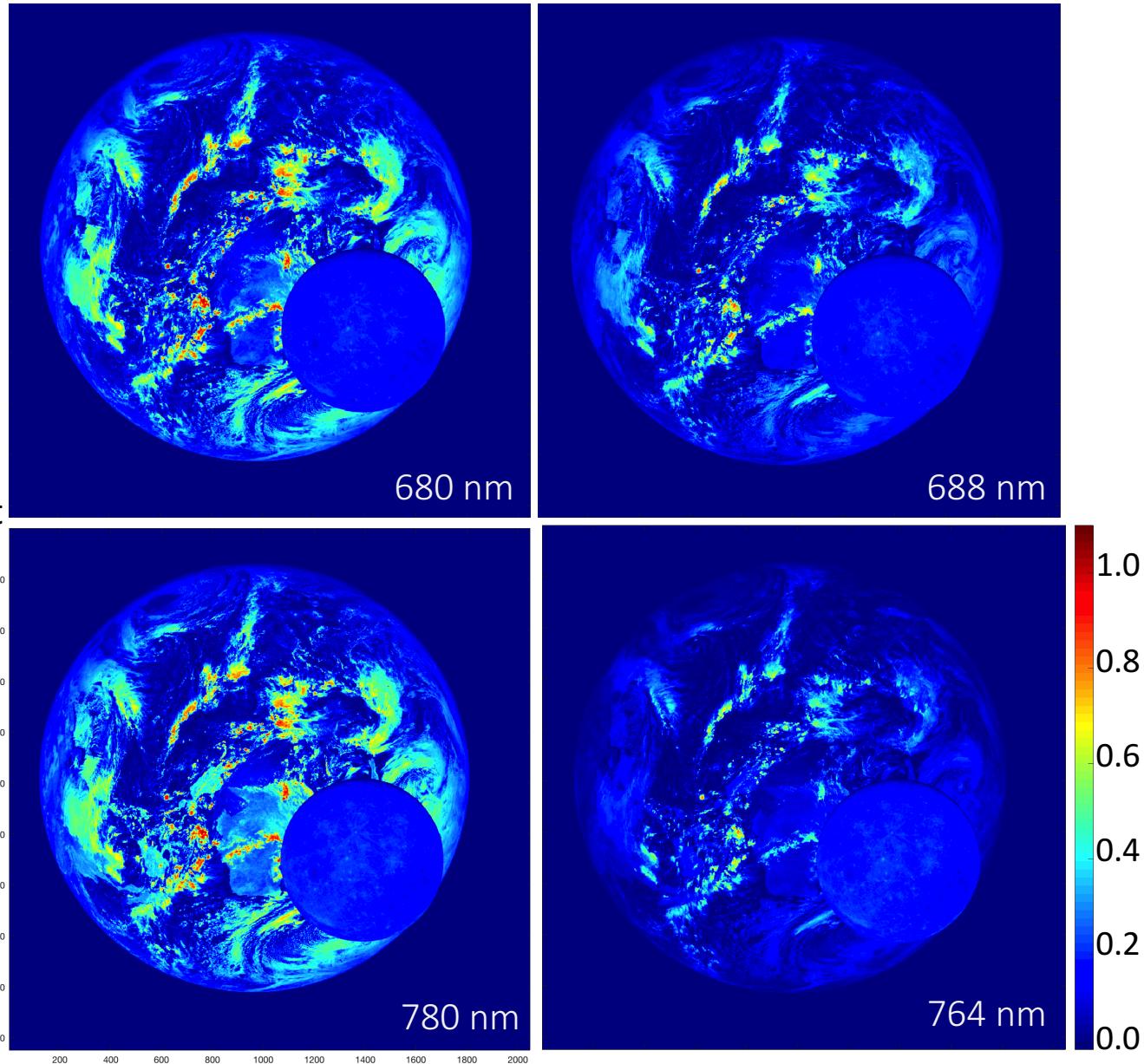
EPIC/DSCOVR  
O<sub>2</sub> channels:

**B-band**  
 $\tau_{\text{O}_2} \approx 0.3$

Reference on left  
( $\tau_{\text{O}_2} = 0$ )

**A-band**  
 $\tau_{\text{O}_2} \approx 0.6$

2017-11-19



# EPIC's A- and B-band channels ... at 11/17 new Moon

EPIC/DSCOVR  
O<sub>2</sub> channels:

B-band

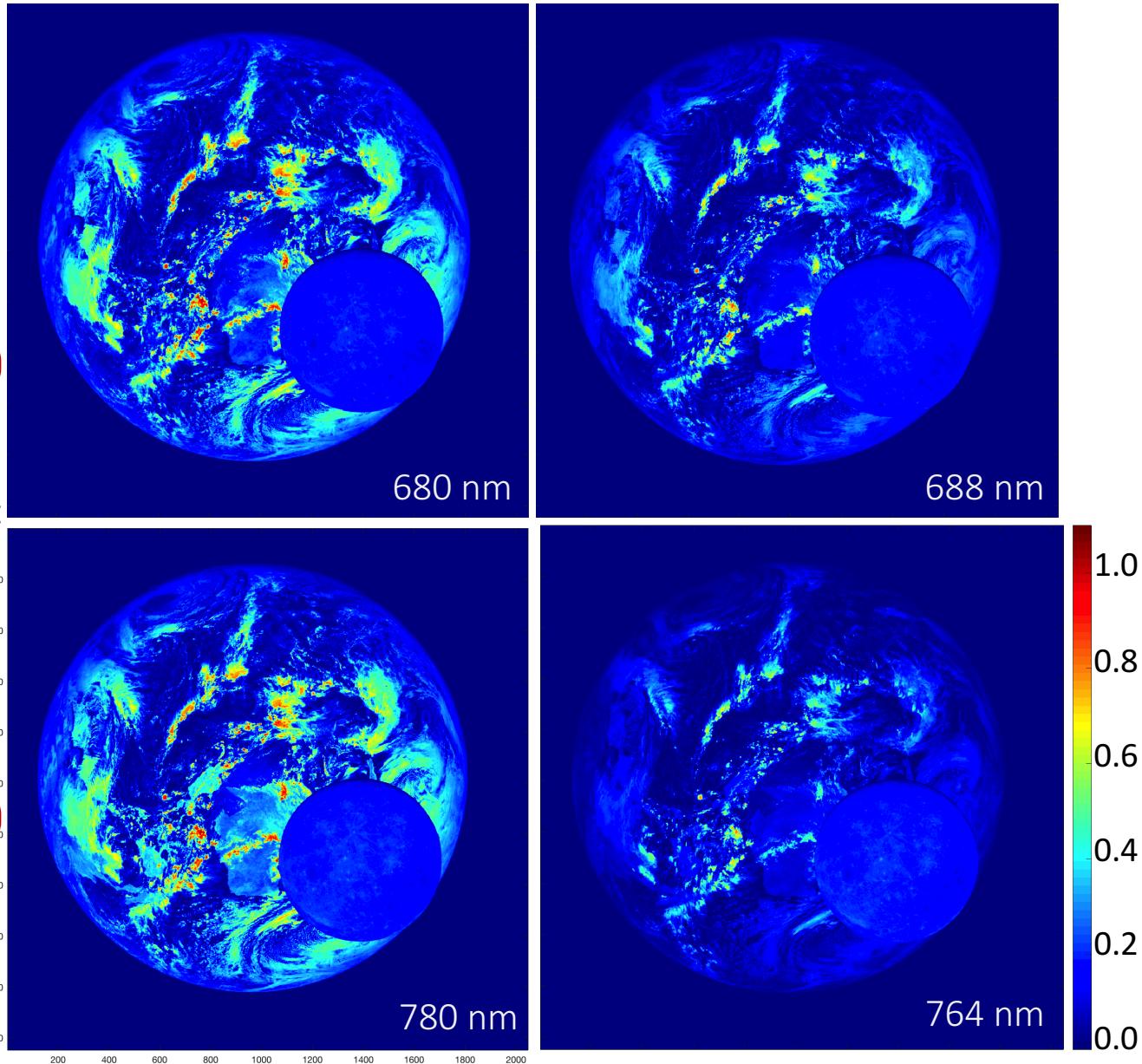
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# EPIC's A- and B-band channels ... at 11/17 new Moon

**EPIC/DSCOVR**  
O<sub>2</sub> channels:

**B-band**

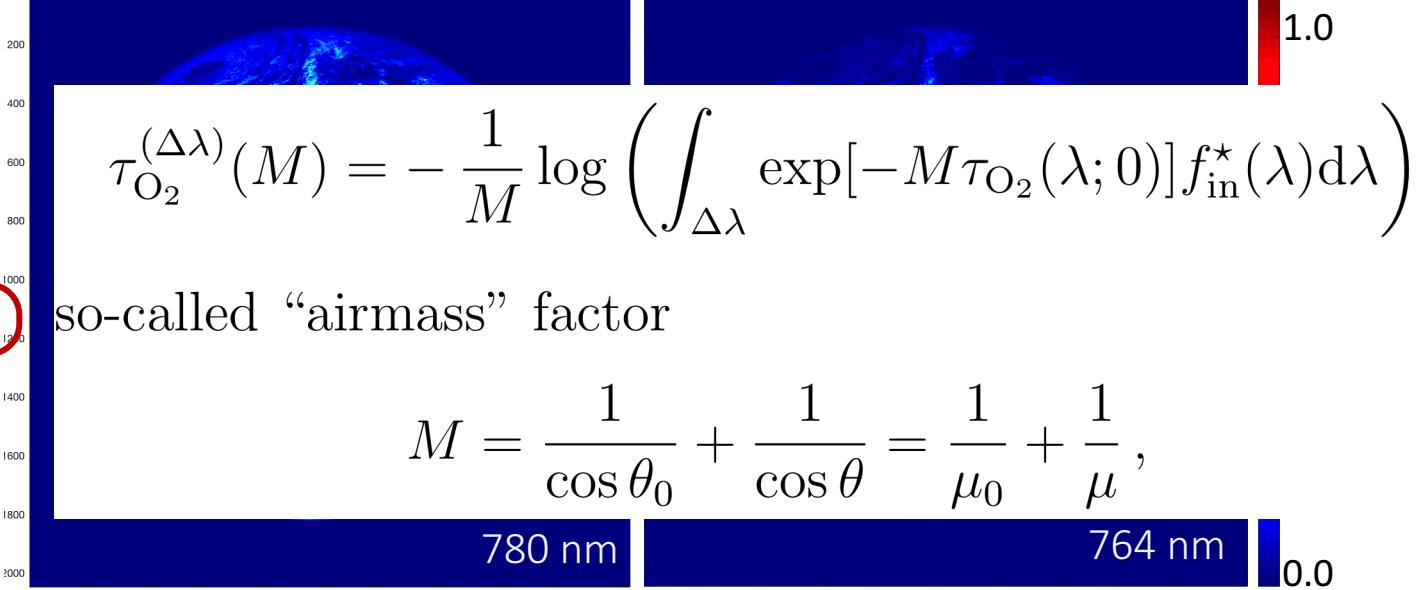
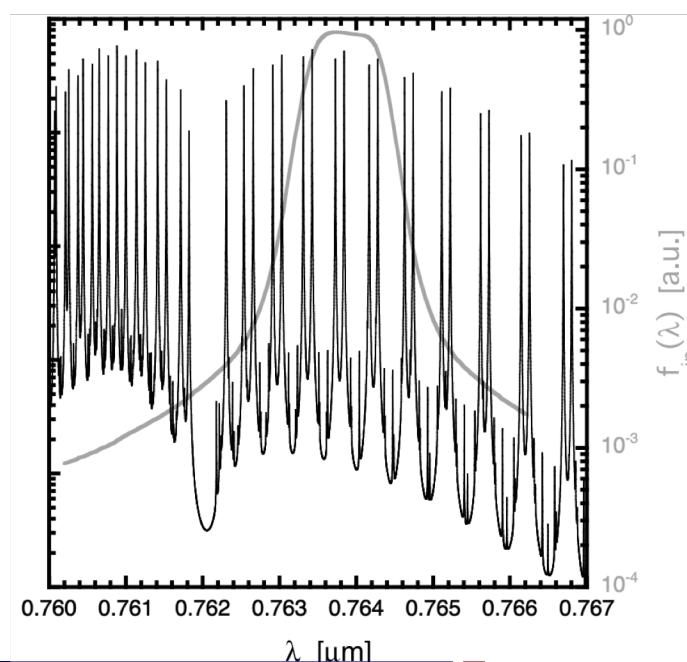
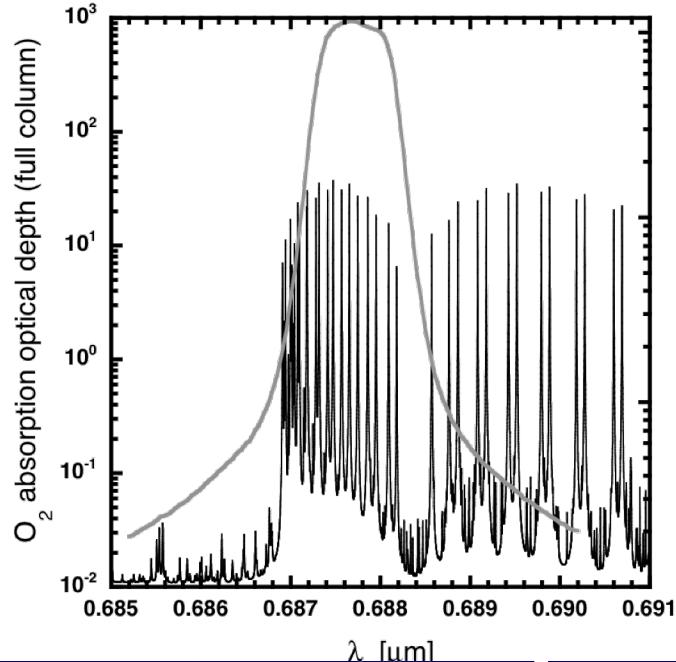
$$\tau_{\text{O}_2} \approx 0.3$$

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**A-band**

$$\tau_{\text{O}_2} \approx 0.6$$

effective optical thicknesses



# Statistical (optimal estimation) approach



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Cloud information content in EPIC/DSCOVR's oxygen A- and B-band channels: An optimal estimation approach

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Alexander Marshak <sup>d</sup>

errors  
sensor → model →

not shown here:  $S_y = S_\varepsilon + S_b$

Bayes' theorem:

PDF of total cost function =

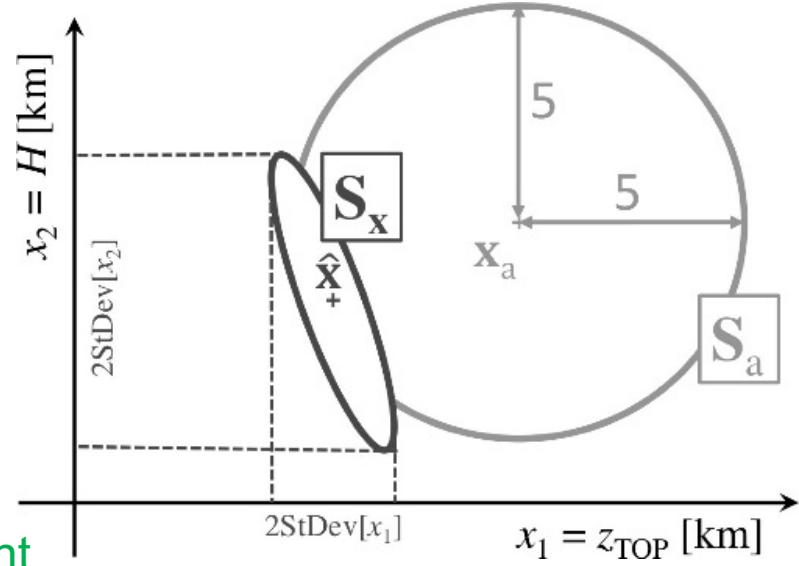
*observations*  
↓

PDF of forward model prediction error on  $y$

× PDF of prior uncertainty on state vector  $x$

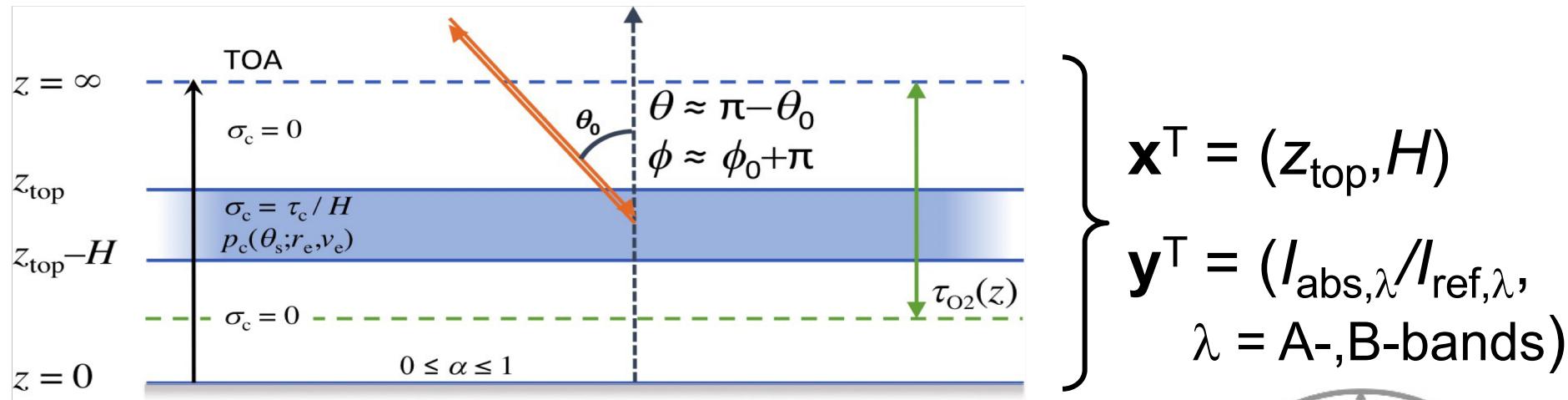
likelihood of  $y$ , given  $x$       prior uncertainty on  $x$

$$p(x|y) = \underbrace{p(y|x)}_{\text{posterior uncertainty on } x, \text{ given } y} \underbrace{p(x)}_{\text{unimportant}} / p(y)$$

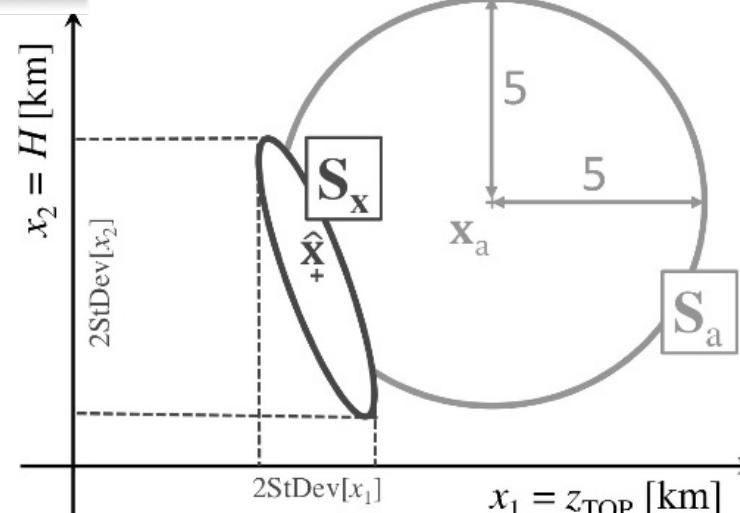


# (Partial) Shannon information content / gain

Information Content (IC) gain or Degrees-Of-Freedom (DOF) per cloud property = ratio of the areas of  $S_a$  and  $S_x$ , projected onto one of the state/x-space axes

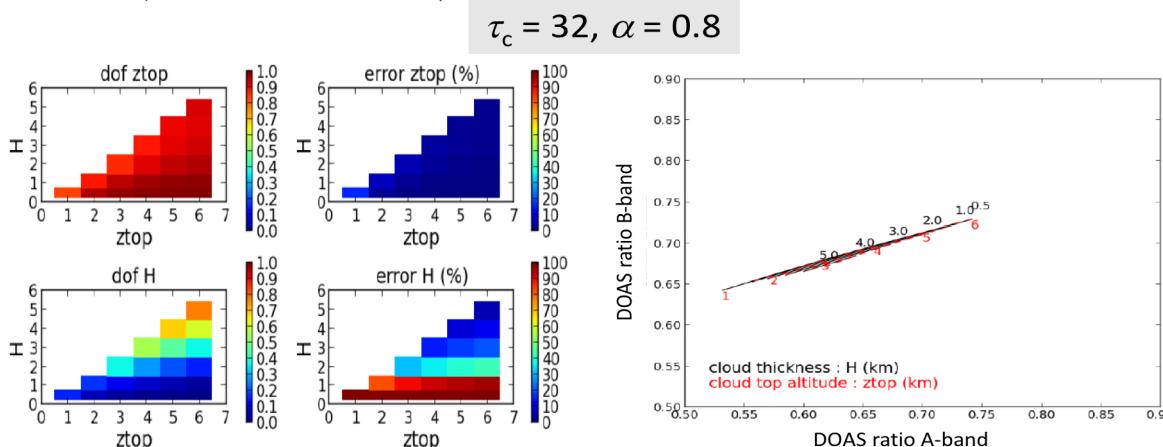
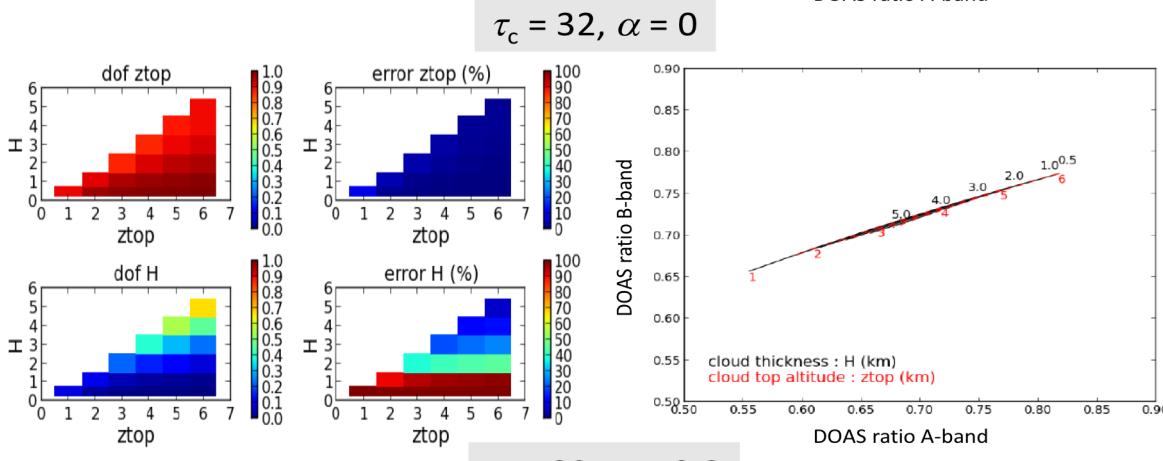
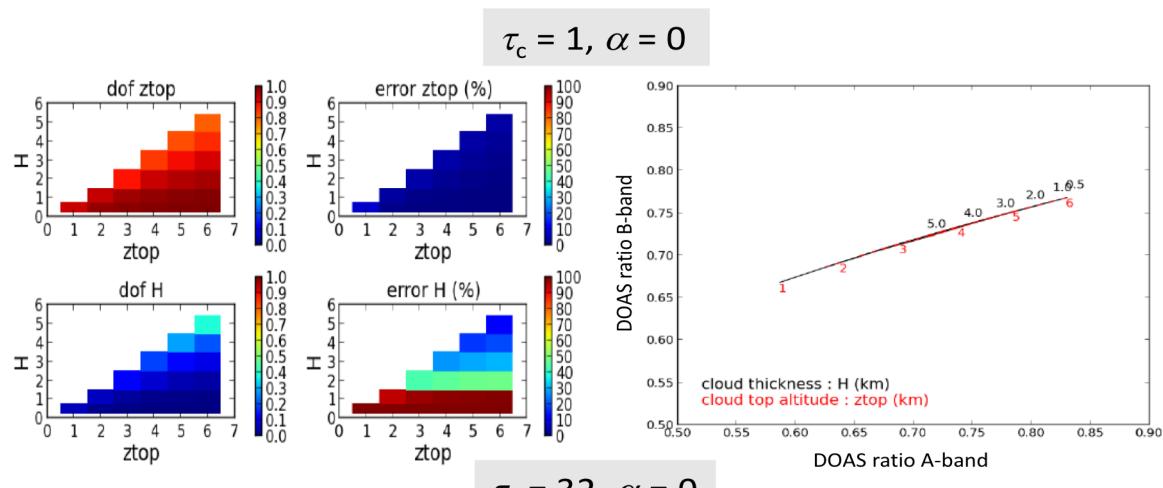


Total information content/gain =  
Ratios of ellipses areas  $|S|$ , i.e., of  
products of minor and major axes of  
the prior-to-posterior PDFs



# Posterior uncertainty of the retrieved cloud properties

$0 \leq \text{pDOF}_i \leq 1$ , for  
 $i = 1, 2$  ( $z_{\text{top}}, H$ ) and  
 $\sigma_{pi} = \sigma_{ai}(1-\text{DOF}_i)^{1/2}$   
 for the standard deviations.



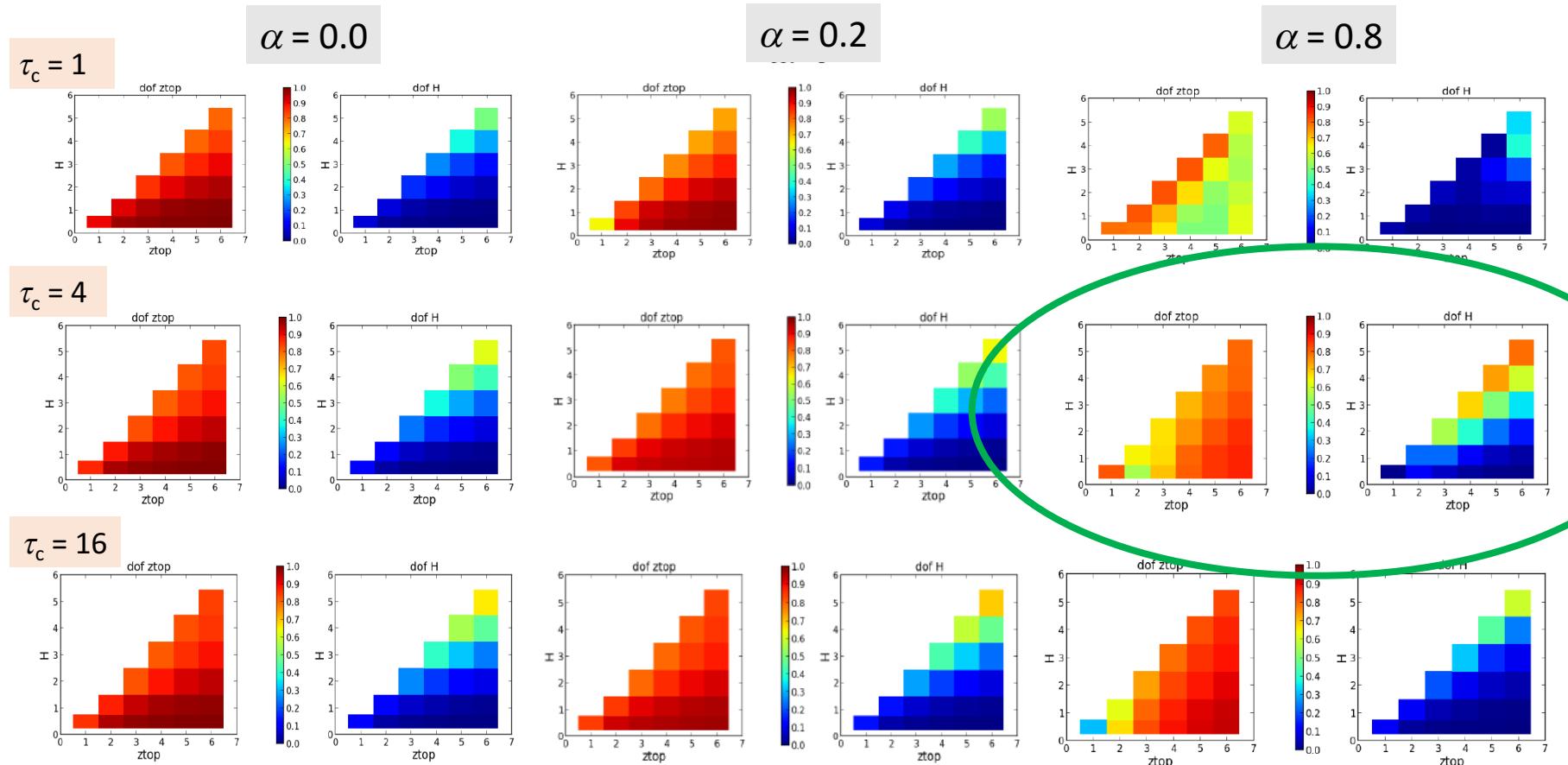
Errors expressed here in %:  $100 \sigma_i / x_i$

“Nakajima-King” plots of DOAS ratios

DOAS: Differential Optical Absorption Spectroscopy

# A sweet spot for $z_{\text{top}}$ and $H$ retrieval?

→ moderately opaque clouds over bright surfaces ...



... a possible application to arctic clouds?

# Conflict with Yang et al. (2013)?

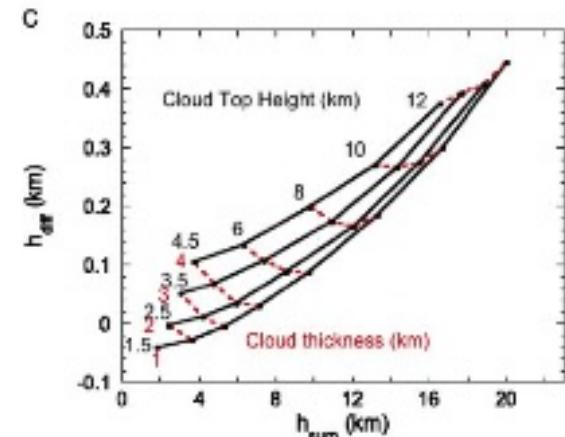
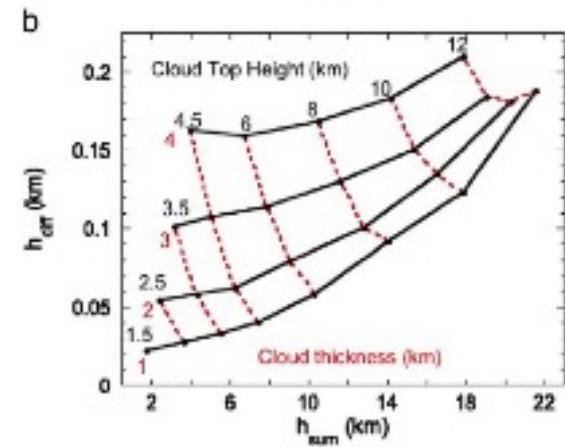
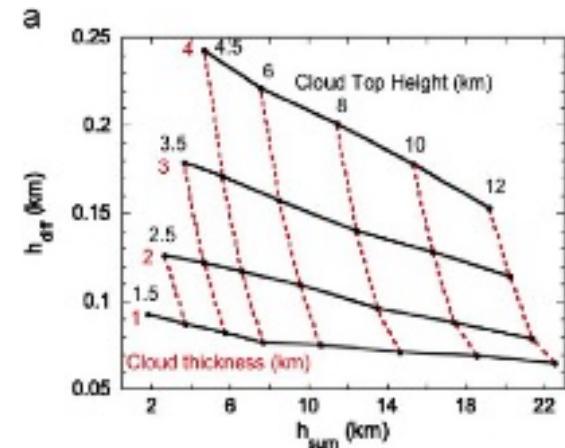
cloud optical thickness (COT)  $\tau_c = 30$

→ not really ...

$$\tau_c = 10$$

ECH: “effective” cloud height  
 $h_{\text{diff,sum}} = \text{CEH}_A \pm \text{CEH}_B$

Factoring in sensor error,  
uncertainty on  $h_{\text{diff}}$  is  $\sim$  vertical axes  
uncertainty on  $h_{\text{sum}}$  is << horizontal axes



# Physical modeling approach

## Assumptions:

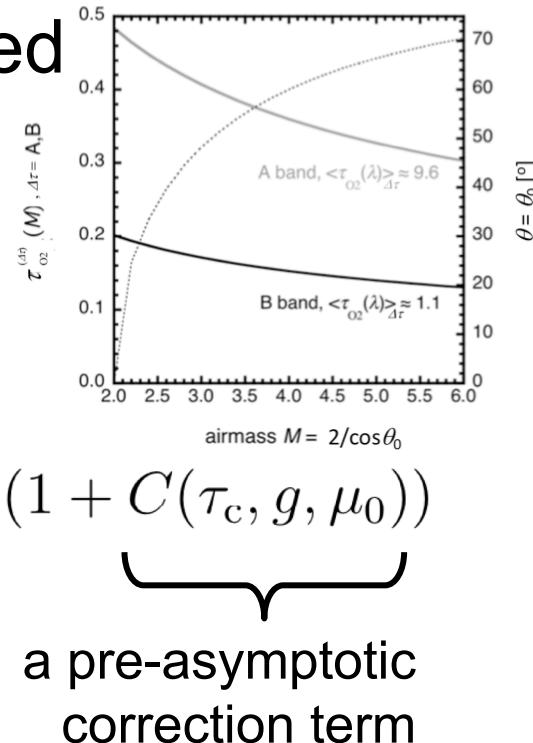
- plane-parallel geometry (1D RT is OK)
- optical thick clouds (asymptotic/diffusion theory)
- dark surface (water)
- “effective”  $O_2$  optical depth for each band ↓
- exponential pressure profile, as needed

... i.e., it's OK to use  $\tau_{O_2}^{(\Delta\lambda)}(M)$  here

$$\begin{aligned} -\log r_\lambda(\Omega; \Omega_0, \tau_c) &\approx (1/\mu_0 + 1/\mu) \tau_{O_2}(\lambda; z_{\text{top}}) \\ &\quad + (\mu + \mu_0) [\tau_{O_2}(\lambda; z)]_{z_{\text{top}}-H}^{z_{\text{top}}} \times (1 + C(\tau_c, g, \mu_0)) \end{aligned}$$

DOAS ratio

... and here

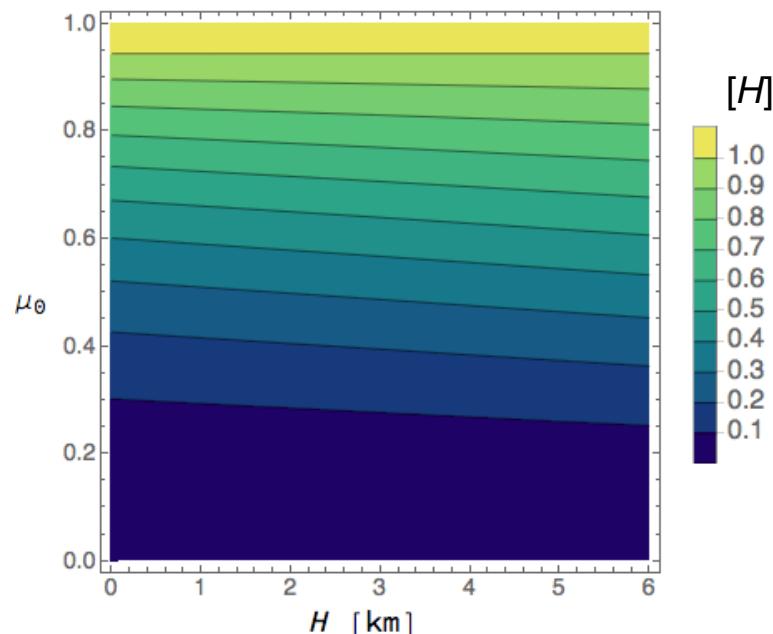


## Physical insights ...

retrieval bias from ignoring in-cloud path length

$$z_{\text{top}}^{(\text{app})} \approx z_{\text{top}} - H_{\text{mol}} \log [1 + \mu_0 \mu (e^{H/H_{\text{mol}}} - 1) \times (1 + C(\tau_c, g, \mu_0))] \\ \approx -\mu_0 \mu H \times (1 + C(\tau_c, g, \mu_0))$$

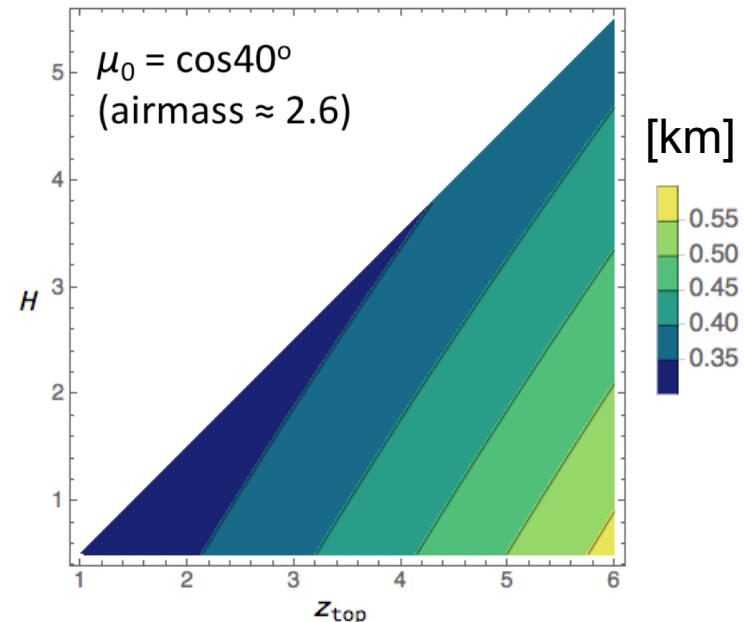
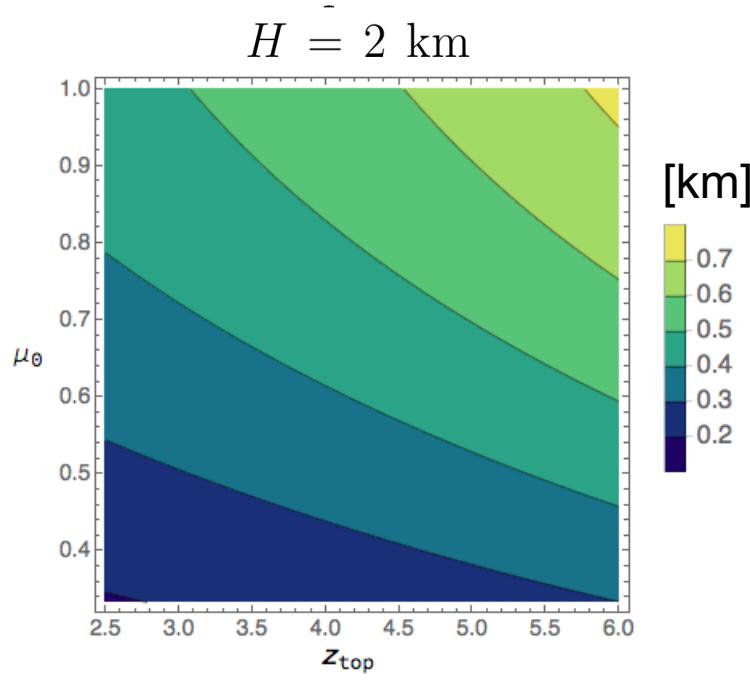
Normalized CTH bias  $(z_{\text{top}} - z_{\text{top}}^{(\text{app})}) / H$  from (19) for EPIC  
 $(\mu_0 = \mu)$ , and  $H_{\text{mol}} = 8$  km.



## Physical insights ...

random retrieval uncertainty resulting from sensor error, assuming 1.5% on DOAS ratio

$$\Delta z_{\text{top}}^{(\text{app})} \approx \frac{0.015 H_{\text{mol}}}{\tau_{\text{O}_2}^{(\Delta\lambda)}} \times \frac{e^{z_{\text{top}}/H_{\text{mol}}}}{2\mu_0 (\mu_0^{-2} + e^{H/H_{\text{mol}}} - 1)}$$



# Summary/outlook

- **Optimal estimation approach**
  - computational (exact) 1D RT model
  - Rodgers' [2000] statistical formalism
- **Physics-based approach**
  - analytical (but approximate) 1D RT model
  - physical insights about biases and sensitivities
- **Both approaches ...**
  - use derivatives of signals w.r.t. cloud properties (a.k.a. Jacobians)
  - account for sensor noise level
  - lead to the conclusion that, under most circumstances, only the cloud top height can be reliably retrieved